

Project no. 2: Test stand for AGV drives

The customer would like to build a test bench to test electric drives for automated guided vehicles (AGV), based on a permanent magnet synchronous motor with a gearbox. The hardware is already prepared, but without a control system. Now, the customer demands a control system for the test-bench.

Test bench is designed as drive-against-drive loading with a permanent magnet synchronous motor as a load machine (Fig. 1). The test procedure should use a cyclic operation, consisting from a short movement followed by an idle time (Fig. 2). At first, a control system for an AGV drive should be designed.

The requirements are:

- drive control should be highly dynamic and precise
- test cycle parameters in Fig. 2 should be settable
- test procedure should be controlled from a remote PC
- test-bench operation should have a possibility to fast-stop the drive (emergency stop) from the PC and locally
- actual status should be displayed on remote PC and locally using LCD and signal lights
- drive should be protected against overload and overspeed

The customer demands a complete software solution for an existing HW with source code (programming language C), including code documentation and user guide.

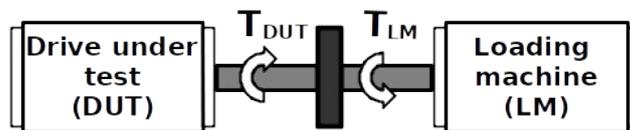


Fig. 1: Test-bench concept

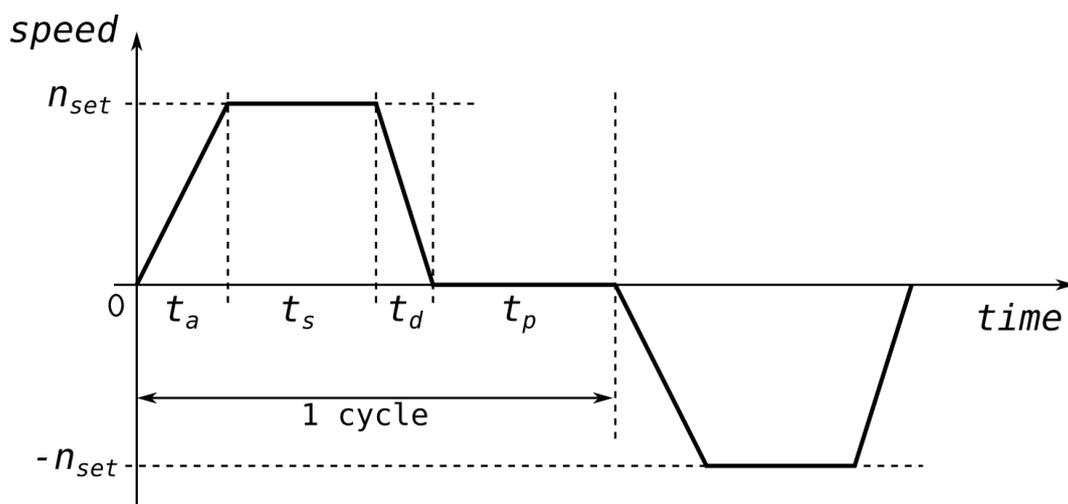


Fig. 2: An example of test cycle

(t_a – acceleration time, t_s – steady state time, t_d – deceleration time, t_p – idle time, n_{set} – set speed)

Task 1 – Missing information

Task 2 – Project management and time schedule 1

Roles assignment:

(name) – (role)

- 1. -
- 2. -
- 3. -
- 4. -
- 5. -
- 6. -

Time schedule - initial

Task & responsible person	Week												
	W1	W2	W3	W4	W5	W6	W7	W8	W9	W10	W11	W12	W13

Task 3 – Meeting with customer - agenda

1.
2.
3.
4.
5.
6.
7.
8.

